"TRADER" SERVICE SHEET

A.C. Mains/Battery Portable

DESIGNED to operate from self-contained dry batteries or from A.C. mains of 200-250 V, 40-100 c/s (but not from D.C. mains) the Vidor CN396 is a suitcase-type portable 2-band superhet employing four all-dry battery valves and a mains rectifier. A warning device causes the speaker to howl if the lid is closed while the set is switched on.

The CN396A is almost identical with the CN396, but the method of fixing the chassis in the case is a little different. The wavehand ranges in both models are 186-550 m and 1,100-1,870 m.

Release date and original price: November, 1949; 12 19s 4d, increased February, 1951, to £13 16s 7d. Purchase tax extra.

CIRCUIT DESCRIPTION

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Tuned frame aerial input L1, C29 (L.W.) precedes a heptode valve (V1, Mullard DK91) which operates as frequency changer with internal coupling. For M.W. operation frame aerial L2 is connected in parallel with L1.

Oscillator grid coil L3 (M.W.) is tuned by C30. For L.W. operation C10 is shunted across L3. Parallel trimming by C31 (M.W.); series tracking by C9. Inductive reaction coupling on M.W. and L.W. by L4.

Second valve (V2, Mullard DF91) is an R.F. pentode operating as intermediate frequency amplifier with tuned transformer couplings C5, L6, C6 and C14, L7, L8, C15.

Intermediate frequency 466 kc/s.

Diode signal detector is part of diode pentode valve (V3, Mullard DAF91). A.F. component in rectified output is developed across manual volume control R9 and passed via A.F. coupling capacitor C18 to control grid of pentode section which operates as A.F. amplifier. I.F. filtering by C16, R8, C17 in diode circuit and C20 in pentode circuit.

D.C. potential developed across R8, R9 is fed

by C16, R3, C17 in diode circuit and C20 in pentode circuit.

D.C. potential developed across R8, R9 is fed back as bias to F.C. valve, giving automatic gain control. The I.F. bias is fixed.

Resistance-capacitance coupling by R11, C21 and R15 between V3 pentode and pentode output valve (V4, Mullard DL94). Fixed tone correction by C22 in anode circuit, and by negative feed-back between V3 and V4 anodes via R14.

For battery operation, power supplies are carried by switches S4(B) and S5(B), which close in the battery positions. For A.C. mains operation S4(M), S5(M) and S6(M) close instead.

H.T. current is then supplied by I.H.C. full-

wave rectifying valve (V5, Mullard EZ41). Smoothing by R20 and electrolytic capacitors C26, C27. Filament current is also taken from the H.T. circuit, the series connected filaments being fed via R18, R19. C24 and C25 ensure a smooth D.C. supply to the filaments which are shunted by R6, R12 and R16 to by-pass the H.T. current. current.

When the lid of the carrying case is closed S7, comprising the lid stay and two springs, also closes, causing positive feed-back via C23 between V4 anode and V3 screen grid and producing a warning note in the speaker if the set is still switched on.

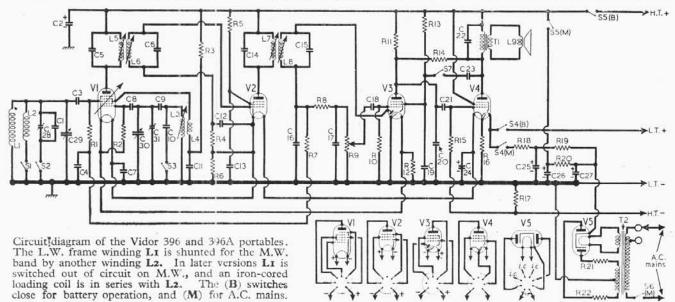
COMPONENTS AND VALUES

CA	PACITORS		Values	Loca tions
	W. trimmer	2000	130pF	D3
	T. decoupling	***	$2\mu F$	C2
		400	100pF	D3
	G.C. decoup.		$0.05 \mu F$	E3
5 1 1st	I.F. trans. t	un- f	65pF	B2
6 5 1	ng	J	65pF	B2
	ament by-pass		0.1µF	E3
V1	osc, C.G.	. awar	100pF	D3
Tr	acker		635pF	E4
0 L.	V. trimmer .	++	540pF	E4
1 Os	c, anode deco	up.	0.1µF	BI
2 V2	G.B. decoup.		0.01µF	E3
3 V2	S.G. decoup.		0.1µF	B1
1 2n	i I.F. trans, to	in- f	65pF	C2
, } i	ng	}	65pF	C2
1111	has marcas	-	100pF	F3
	. by-passes	{	100pF	D5
s A.	F, coupling		$0.001 \mu F$	G4
V3	S.G. decoup.	0.00	$0.05 \mu F$	G3
	. by-pass		65pF	G3
1 A.	, coupling	84.0	0.01µF	G3
	ne corrector	77.5	0.001µF	G4
3 Al:	arm coupling	***	$0.02 \mu F$	G4
1 tr	C, smoothing		$200 \mu F$	B2
5* 5	t, smoothing		$25\mu F$	H6
6* LH	T. smoothing	5	40 µ F	H6
17.00	경기를 잃었다. 그리고 하다 하다.		$40\mu F$	H6
	V, aerial trim	4995	50pF	A1
	rial tuning		§523pF	A2
	e, tuning	***	§523pF §523pF	A1
31; M.	W. osc. trimr	ner	50pF	A1

*	Electrolytic.	† Variable.	‡ Pre-set.
	s "Swing"	value, min.	to max.



	RESISTORS		Values	Loca- tions
R1 R2 R3 R4 R5 R6 R7 R8 R9 R10 R11 R12 R13 R14 R15 R17 R16 R17 R18	V1 C.G V1 osc. C.G. Osc. anode feed V2 C.G. V2 S.G. feed Fil. shunt A.G.C. decoup, I.F. stopper Volume control V3 C.G V3 anode load Fil. shunt V3 S.G. feed Neg. f-b V4 C.G. Fil. shunt V4 C.B L.T. Smoothing		4·7MΩ 100kΩ 22kΩ 4·7MΩ 100kΩ 1kΩ 2·2MΩ 1MΩ 4·7MΩ 270kΩ 270kΩ 1MΩ 2-2MΩ 1MΩ 2-2MΩ 1MΩ 1-8kΩ 1-50Ω 1-50Ω 1-5kΩ 1-50Ω 1-5kΩ	E3 E3 F4 E3 F3 E3 F3 D5 G4 G4 G3 G3 G3 G3 G3 F3 J6
R20 R21 R22	H.T. smoothing Surge limiters	{	$\frac{2.7 \text{k}\Omega}{100\Omega}$ $\frac{100\Omega}{100\Omega}$	H6 J6 J6



OTE	ER COMPONENTS	Values (ohms)	Loca-
L1 L2 L3 L4 L5 L6 L7 L8 L9	L.W. frame aerial M.W. frame aerial Osc. tuning coil Osc. reaction 1st I.F. trans. {Pri. Sec. } 2nd I.F. trans. {Pri. Sec. Speech coil	15 0 2 0 1 5 1 3 20 0 20 0 20 0 20 0 20 0 3 2	E4 E4 B2 B2 C2 C2 G5
T1	O.P. trans. {Pri. Sec. (Primary, total	580 0 Very low 150 0	G4
T2 S1-S6	H.T. sec. total heater sec W'band and power	200 0 0 8	H 3
87	switches Alarm switch	=	Dit

VALVE ANALYSIS

Valve voltages and currents given in the table Valve voltages and currents given in the table below are those quoted by the manufacturers and were taken with the receiver connected to A.C. mains and the mains adjustment set to the appropriate tapping. The volume control and gang were turned to maximum but there was no signal input. Voltage readings were taken on the 1,000 V range of a Model 7 Avometer, charsis being the negative connection. Readings tallen with the receiver operating from a new set of batteries were slightly lower than those in the table.

Valves		Anode		Sereen		Cath.
		V	mA	7.	mA.	V
VI DK91	211	83	0.21	41	1.4	122
V2 DF91	255	83	1.0	32	0.34	
V3 DAF91	10000	11	0.18	14	0:5	-
V4 DL94	1000	81	4.4	83	0.78	1000
V5 EZ41	1971	122*	-	-		108

· Each anode, A.C.

DISMANTLING THE SET

Removing Chassis.—Lift up the battery compartment cover, unplug H.T. and L.T. leads and

ment cover, unplug H.T. and L.T. leads and remove batteries; remove two small metal brackets, secured by screws to inside edges of lid; release lid stay from left-hand side of lid, held by single screw, and prise out frame aerial cover from inside of lid; unsolder the three aerial leads from their tags inside the lid.

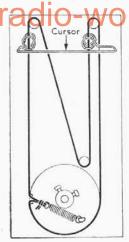
inside the lid; release mains lead from clip in right-hand front

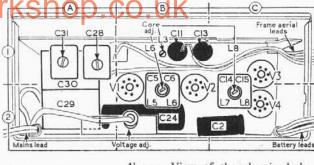
corner of battery compartment;
slacken the two large knurled-head nuts, accessible through the battery compartment, which hold the chassis to the front and back of the carrying case;
slide the chassis to the right, unclipping the two leads, now made accessible, from the lid stay switch

stay switch.

Stay switch.

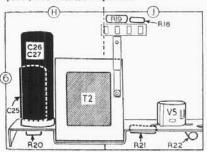
When replacing, the left-hand frame aerial tag
should have the lead from \$1 connected to it,
the central tag takes the earth lead, and the
right-hand tag the lead from C28.





Left: The cursor cord drive system, as seen from the front after removing the chassis unit.

Removing Speaker .- Unsolder the two leads from the tags on the output transformer; move the two 4BA nuts, with shake-proof washers, holding the speaker to the metal panel, and withdraw speaker.



The power unit, viewed in roughly the same position as the under-chassis view below.

When replacing, the output transformer should be at the back, furthest away from the con-trols, and the blue speaker lead should be connected to the same tag as C22, C23.

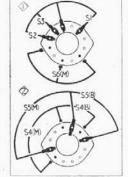
GENERAL NOTES

Switches.—\$1-\$3 are the waveband switches, and \$4(B)-\$6(M) are the battery/mains changeover switches, ganged in two six-position rotary
units. These are indicated in our underside view
of the chassis, and shown in detail in the
diagrams inset beside it.

The control knob is continuously rotatable,
and has two "off" positions; then on one side
of each "off" position are the M.W. and L.W.
positions for battery operation, while on the

-C21 -RIO

RII



Left: Three-quarter underside view of the chassis assembly, with the power unit removed, seen from one side to show the underside of the valve holders. Right : Waveband and mains/battery switch units, viewed from the same direction.

1... R3

Above: View of the chassis deck, showing the upper side of the valve All trimmers are shown.

other side are the same waveband positions for mains operation.

other side are the same waveband positions for mains operation.

In both M.W. positions S1 is closed, and in both L.W. positions S2 and S3 are closed. For bottery operation, S4(B) and S5(B) close; or for mains operation S4(M), S5(M) and S6(M) close, as indicated by the lettered suilixes.

Batteries.—The L.T. unit is a Vidor type L5048 dry battery rated at 7.5 V. It is fitted with a 2-pin socket, of which the thicker pin is the positive. The H.T. unit is a Vidor type L5512, rated at 90 V. It is fitted with a non-reversible 3-pin socket, of which the centre pin is used only for location.

Chassis Divergencies.—In late versions the practice of shunting the L.W. frame winding with the M.W. winding for M.W. operation, as in our sample, has been abandoned, and independent frame windings are used, an additional switch being provided on the waveband switch unit to switch the L.W. winding in and out of circuit.

In these versions, also, an iron-cored loading coil is connected in series with the bottom end of the M.W. frame winding. The core is adjusted during alignment at the same frequency

In the LN896A, two domed feet beneath the

In the LN396A, two domed feet beneath the carrying case have to be unscrewed before the chassis can be withdrawn.

Cursor Drive Cord Replacement.—About 30 inches of high-grade plaited and waxed flax fishing line is needed for a new cord, and it is run as shown in the sketch inset beside the plan chassis view above, which is drawn as seen from the front with the gang at maximum.

To gain access to the drive it is necessary to dismount the chassis from the metal panel on which it is mounted. It is held only by three 4BA nuts and two control knobs, but it is advisable to disconnect several leads going to other units in order to obtain freedom of movement. movement.

CIRCUIT ALIGNMENT

To gain access to the core and trimmer adjustments the chassis should be removed from its carrying case. Before aligning the I.F. stages the cores should be carefully freed by melting the wax with which they are sealed.

I.F. Stages.—Switch set to L.W., tune to 2,000 m on the scale and turn volume control to maximum. Connect the "live" side of C30 to chassis, and the signal generator, via a 100pt capacitor in the "live" lead, to V1 control grid (pin 6) and chassis. Feed in a 456 kc/s (657.8 m) signal and adjust the cores of L8 (location reference C2), L7 (F3), L6 (B1) and L5 (F3) for maximum output, reducing the input as the circuit scome into line to avoid A.G.C. action. Re-seal the cores with soft wax.

R.F. and Oscillator Stages.—Check that with

R.F. and Oscillator Stages.—Check that with the gang at maximum capacitance, the cursor coincides with the 550 m mark on the M.W.

coincides with the 550 m mark on the M.W. scale.

M.W.—Switch set to M.W., remove the short-circuit from C30 and transfer the signal generator leads to frame aerial, placing them in close proximity to the windings in the lid of the carrying case. Tune to 200 m (1,500 kc/s) on scale, feed in a 200 m (1,500 kc/s) signal and adjust C31 (A1) for maximum output. Tune set to 550 m, feed in a 550 m (545.45 kc/s) signal and adjust the core of L3 (B1) for maximum output, "rocking" the gang slightly after each adjustment. Repeat these adjustments.

L.W.—Switch set to L.W., tune to 1,200 m, feed in a 1,200 m (250 kc/s) signal and adjust C38 (A1) for maximum output.